

\Rightarrow exact sequence of vector bundles

trivial bundle

$$\rightarrow S^0(V^v) \otimes \Lambda^2(V^v) \rightarrow S^0(V^v) \otimes V^v[1] \rightarrow S^0(V^v) \rightarrow \mathbb{R}$$

\Rightarrow

$$\rightarrow \Gamma(\quad) \rightarrow \Gamma(\quad) \rightarrow \Gamma(\quad) \xrightarrow{\epsilon} C^\infty(X)$$

$\Gamma(S^0(V^v) \otimes \Lambda^2(V^v[1]))$

! This exactness when passing to sections holds in the smooth setting!

So it suffices to show:

$$H^k(\underbrace{S^0(V_x^v) \otimes \Lambda^2(V_x^v[1])}_{K(V)}) = \begin{cases} \mathbb{R} & k=0 \\ 0 & k \neq 0 \end{cases}$$

chain homotopy H between 0 and a map Φ to be determined.

$H: K(V^r) \rightarrow K(V^r)$ of degree -1 , a graded derivation, hence determined on generators

$$S^k(V^r) \otimes \Lambda^l(V^r[1])$$

$$\xi \in V^r \quad H(\xi \otimes 1) := 1 \otimes \xi[1]$$

$$H(1 \otimes \xi[1]) := 0$$

$$\begin{aligned} \Phi &:= dH + Hd \\ &= [d, H] \end{aligned}$$

calculate, using the fact that

\rightarrow graded commutator, hence since d & H are graded derivations (of deg $+1$ resp. -1)

$$\Phi = [d, H] \text{ graded derivation of deg } 0.$$

$$\Phi: S^k(V^r) \otimes \Lambda^l(V^r[1]) \hookrightarrow$$

is multiplication by $(k+l)$.

$\Rightarrow \Phi$ is chain homotopy to 0; hence it induces

same map on cohomology,

Hence cohomology is concentrated on $l=0, k=0$ \square

Recall: Cor: V vector bdl., section α
 \downarrow
 X zero section Z

$$\mathcal{O}(X) \otimes_{\mathcal{O}(V), \alpha^*}^h \mathcal{O}(X) \cong \left(\Gamma(\wedge^\bullet(V^v[1])), \mathcal{L}_\alpha \right)$$

$$\mathcal{L}_\alpha: \wedge^k(V^v[1]) \rightarrow \wedge^{k-1}(V^v[1])$$

in particular:

$$\mathcal{O}(\underbrace{d\text{Crit}(S)}_{\text{derived critical locus}}) := \mathcal{O}(X \cap \text{graph}(dS)) = \left(\Gamma(X, \wedge^\bullet(TX[1])), \mathcal{L}_{dS} \right)$$

$$dS: X \rightarrow T^*X$$

diff. graded \mathcal{A}
 algebra of
 functions on
 $d\text{Crit}(S)$.

If ds is transversal to zero section, then

$$H^k(\Gamma(\wedge^0(TM[1])), L_{ds}) = \begin{cases} C^\infty(\text{Crit}(s)) & k=0 \\ 0 & k \neq 0 \end{cases}$$

originally, we defined $\text{Obs}^{\text{cl}} := C^\infty(\underbrace{\text{Crit}(s)}_{\text{space of classical fields}})$

from the derived point of view we redefine

$$\underbrace{\text{Obs}^{\text{cl}}}_{\text{classical observables}} := \mathcal{O}(d\text{Crit}(s)) = (\Gamma(\wedge^1(TX[1])), L_{ds}).$$

classical observables

more explicitly:

$$\begin{array}{ccccccc} \text{deg} & & & & & & \\ & -3 & & -2 & & -1 & \\ & \Gamma(\wedge^3 TX) & \xrightarrow{ds} & \Gamma(\wedge^2 TX) & \xrightarrow{ds} & \Gamma(TX) & \xrightarrow{ds} & C^\infty(X) \\ & \uparrow & & \uparrow & & \uparrow & & \\ & & & & & & & \text{a lot of structure,} \\ & & & & & & & \text{dga} \\ & & & & & & & \text{+ (shifted) Lie algebra} \\ & & & & & & & \mathcal{O} \end{array}$$

poly vector field

vector fields

digression on symplectic manifolds
(classical mechanics)

Def: M mfd. \mathcal{A} symplectic structure on M

is $\omega \in \Omega^2(M)$ s.t.

(i) $d\omega = 0$

(ii) $T(TM) \xrightarrow{\cong} \Omega^1(M)$

$X \mapsto L_X \omega$

$(L_X \omega)(Y) = \omega(X, Y)$

Rem: { physical states
of a mechanical
system }

is typically a $\begin{matrix} \uparrow & \uparrow \\ \text{vector fields} \end{matrix}$ symplectic mfd.

Ex: a point particle moving in a Riem. mfd X
{ states } = { geodesics in X } $\cong TX \underset{\text{Riem. metric}}{\cong} T^*X$

for any mfd X (without any structure),
 there is a preferred symplectic structure
 on T^*X :

$$\omega = d\Theta \in \Omega^2(T^*X)$$

$$\Theta \left(\underset{\substack{\uparrow \\ X}}{(x, \xi)}, \underset{\substack{\uparrow \\ T_{(x, \xi)}(T^*X)}}{v} \right) := \sum_{i=1}^n (\pi_i(v)) \in \mathbb{R}$$

$$\pi: T^*X \rightarrow X \quad \text{differential } \pi_x: T_{(x, \xi)} T^*X \rightarrow T_x X$$

we are interested in the time development of
 $\phi \in M$ (symplectic mfd).

Def: given $f \in C^\infty(M)$, the associated
Hamiltonian vector field X_f

is determined by $\iota_{X_f} \omega = -df$

Ex: $M = T^* \mathbb{R} = \overleftarrow{\mathbb{R}}^{\text{base}} \times \overleftarrow{\mathbb{R}}^{\text{fiber}}$ ↖ convention to be motivated later.

Coordinate functions: q, p
↑ "position" ↑ "momentum"

homework: i) $\Theta = p dq$ and hence $\omega = d\Theta = dp \wedge dq$

ii) $X_q = -\frac{\partial}{\partial p}$, $X_p = \frac{\partial}{\partial q}$.

Think of functions on a symplectic manifold M as "observables".

Def: Poisson bracket: $\{, \}$: $C^\infty(M) \times C^\infty(M) \rightarrow C^\infty(M)$
 M symplectic

$$\{f, g\} := X_f g = dg(X_f) = -(\mathcal{L}_{X_g} \omega)(X_f) = -\omega(X_g, X_f) = \omega(X_f, X_g)$$

Lem: the Poisson bracket gives $C^\infty(M)$ the structure of a Lie algebra, i.e.

- (skew-symmetry) $\{f, g\} = -\{g, f\}$

- (Jacobi identity): $\{f, \{g, h\}\} + \{g, \{h, f\}\} + \{h, \{f, g\}\} = 0$

$$\{f, \{g, h\}\} = \{f, g\}h + \{g, f\}h + \{g, h\}f$$

i.e. $\{f, -\}$ is a derivation w.r.t. to the Lie bracket.

Pf: homework

Lem: $C^\infty(M) \rightarrow T^*(TM)$
 $\{f, g\} \mapsto X_f$ Lie bracket of vector fields
 is a Lie algebra homomorphism,
 given by $\{f, g\}$ Lie alg.

$$\text{i.e. } [X_f, X_g] = X_{\{f, g\}}$$