

# **WENO Shock-Fitted Solution to 1-D Euler Equations with Reaction**

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Tenth SIAM International Conference on Numerical  
Combustion

Sedona, Arizona  
10 May 2004



## Introduction

- Euler equations with reaction.
- Simple two species irreversible exothermic reaction.
- High order numerical method to resolve behavior.
- Shock fitting to maintain order in presence of discontinuity.
- ZND structure for  $f=1.8$  and  $1.6$ .

## Review

- Fickett and Davis, *Detonation: Theory and Experiment*, 1979.
- LeVeque, *Numerical Methods for Cons. Laws*, 1992
- Osher and Fedkiw, *L.S.M. Dyn. Imp. Surfaces*, 2003
- Jiang and Shu, *J. Comp. Phys.*, 1996
- Short and Sharpe - 1D linear stability results
- Bdzil - Shock Change Equation

## Numerical Difficulties

- PDE versus conservation at the shock.
- Shock capturing - oscillations.
- Shock tracking - evolution of shock location on fixed grid.
- Shock fitting - numerical grid aligned with shock locus.

## Governing Equations in 1-D

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho u) = 0$$

$$\frac{\partial}{\partial t} (\rho u) + \frac{\partial}{\partial x} (\rho u^2 + p) = 0$$

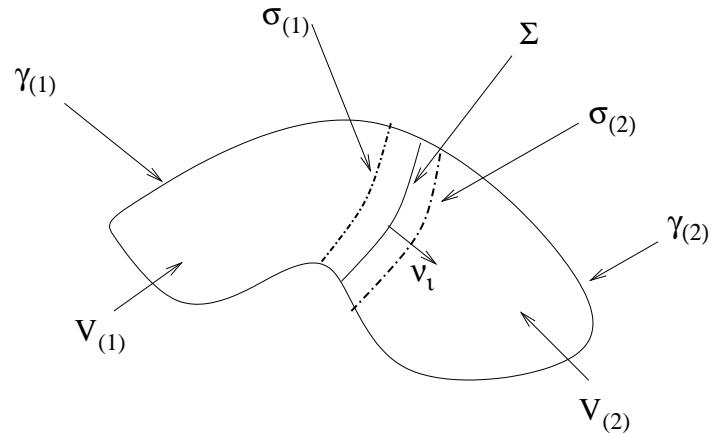
$$\frac{\partial}{\partial t} \left( \rho \left( e + \frac{u^2}{2} \right) \right) + \frac{\partial}{\partial x} \left( u \left( \rho \left( e + \frac{u^2}{2} \right) + p \right) \right) = 0$$

$$\frac{\partial}{\partial t} (\rho \lambda) + \frac{\partial}{\partial x} (\rho \lambda u) = k \rho (1 - \lambda) \exp \left( \frac{-E \rho}{p} \right)$$

$$p = \rho R T \quad e = \frac{1}{\gamma - 1} p / \rho - \lambda q$$

# Jump Conditions

Governing PDE's do not hold over a discontinuity - must appeal to integral formulation.



$$\frac{d}{dt} \int_{M\mathbf{V}} F dV = \underbrace{\int_{M\mathbf{V}} B dV}_{\text{volume forces}} + \underbrace{\int_{MS} T_i n_i dS}_{\text{surface forces}}$$

$$[F(D_i - v_i) + T_i] = 0$$

$$[\rho(D - u)] = 0$$

$$[\rho u(D - u) - p] = 0$$

$$[\rho \left( e + \frac{u^2}{2} \right) (D - u) - up] = 0$$

$$[\rho \lambda(D - u)] = 0$$

This gives  $\rho(D)$ ,  $u(D)$ ,  $p(D)$ ,  $\lambda(D)$  given the quiescent state.

## Wave Frame Transformation

$$\left. \begin{array}{l} \bar{x}(x, t) = x - s(t) \quad -\infty < x < +\infty \\ \bar{t}(x, t) = t \end{array} \right. \text{ all } x \text{ and } t, \quad \left. \begin{array}{l} \frac{\partial f}{\partial t} = \frac{\partial \bar{f}}{\partial \bar{x}} \frac{\partial \bar{x}}{\partial t} + \frac{\partial \bar{f}}{\partial \bar{t}} \frac{\partial \bar{t}}{\partial t} \\ = \frac{\partial \bar{f}}{\partial \bar{x}} (-\dot{s}(t)) + \frac{\partial \bar{f}}{\partial \bar{t}} \\ = -D \frac{\partial \bar{f}}{\partial \bar{x}} + \frac{\partial \bar{f}}{\partial \bar{t}} \end{array} \right.$$

$$\left. \begin{array}{l} \frac{\partial f}{\partial x} = \frac{\partial \bar{f}}{\partial \bar{x}} \frac{\partial \bar{x}}{\partial x} + \frac{\partial \bar{f}}{\partial \bar{t}} \frac{\partial \bar{t}}{\partial x} \\ = \frac{\partial \bar{f}}{\partial \bar{x}} \end{array} \right.$$

$$\frac{\partial \rho}{\partial \bar{t}} + \frac{\partial}{\partial \bar{x}} (\rho u - D\rho) = 0$$

$$\frac{\partial}{\partial \bar{t}} (\rho u) + \frac{\partial}{\partial \bar{x}} (\rho u^2 + p - D\rho u) = 0$$

$$\frac{\partial}{\partial \bar{t}} \left( \rho \left( e + \frac{u^2}{2} \right) \right) + \frac{\partial}{\partial \bar{x}} \left( u \left( \rho \left( e + \frac{u^2}{2} \right) + p \right) - D\rho \left( e + \frac{u^2}{2} \right) \right) = 0$$

$$\frac{\partial}{\partial \bar{t}} (\rho \lambda) + \frac{\partial}{\partial \bar{x}} (\rho \lambda u - D\rho \lambda) = M\dot{\omega}$$

# Shock Change Equation

At the shock,  $\rho u = f(D)$  according to the jump conditions.

$$\begin{aligned}\frac{d}{dt}(\rho u)\Big|_{x=s} &= \frac{dD}{dt} \frac{d}{dD}(\rho u)\Big|_{x=s} \\ &= \frac{\partial}{\partial t}(\rho u)\Big|_{x=s} + D \frac{\partial}{\partial x}(\rho u)\Big|_{x=s}.\end{aligned}$$

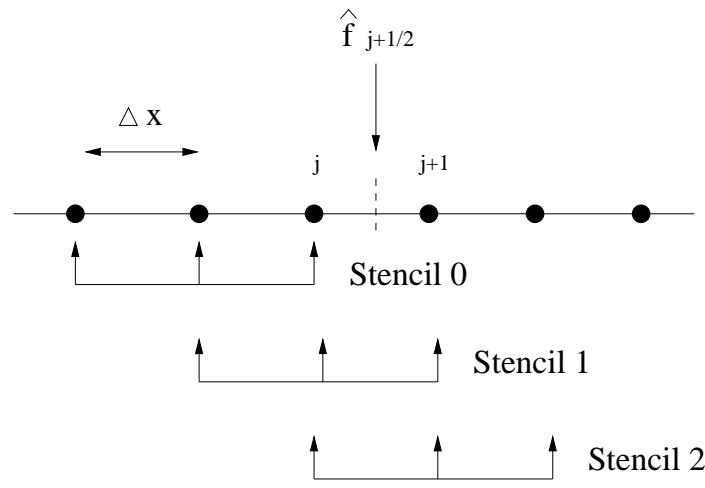
Also the momentum equation gives

$$\frac{\partial}{\partial t}(\rho u)\Big|_{x=s} = - \frac{\partial}{\partial x}(\rho u^2 + p)\Big|_{x=s}.$$

Combining the two gives

$$\frac{dD}{dt} = \left( \frac{d}{dD}(\rho u) \right)^{-1} \left( \frac{\partial}{\partial x} (D\rho u - \rho u^2 - p) \right) \Big|_{x=s}.$$

# Numerics: WENO5 Mapped



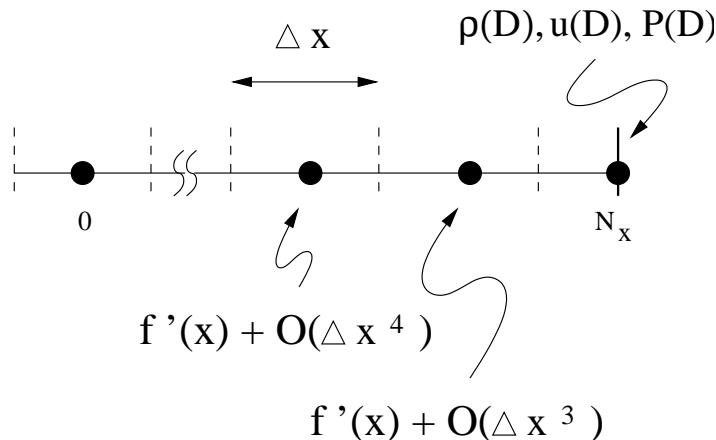
$$\frac{df}{dx} \Big|_{x_j} = \frac{\hat{f}_{j+1/2} - \hat{f}_{j-1/2}}{\Delta x} \quad \text{and}$$

$$\hat{f}_{j\pm 1/2} = \sum_{k=0}^2 \omega_k^{(M)} \hat{f}_{j\pm 1/2}^k,$$

where  $\omega_k^{(M)}$  approximates the ideal weights to high order in smooth region of the flow.

- Conservative numerical scheme.
- Fifth order even near critical points of order one.
- Points near shock must still be considered.

## Numerics: Boundary Points



- Third and fourth order one-sided derivatives at boundary points.
- Spatial order of the scheme is at best third order globally.
- At the shock, conserved variables are functions of  $D$  and the quiescent state.
- $\frac{\partial}{\partial x}$  at  $x = s$  for shock change equation calculated to third order.

## Numerics: Lax-Friedrichs Flux

To properly discretize this system which involves both left and right traveling waves, use the Local Lax-Friedrichs flux:

$$f^\pm = f \pm \alpha u \quad \text{where} \quad \alpha = |u - D| + c,$$

the maximum wave speed magnitude. The numerical flux  $\hat{f}$  is then found using WENO5M for both the  $f^+$  and  $f^-$  LLF:

$$\hat{f} = \frac{1}{2}(\hat{f}^+ + \hat{f}^-)$$

## Numerics: Runge-Kutta Time Integration

Integration in time using third-order TVD Runge-Kutta:

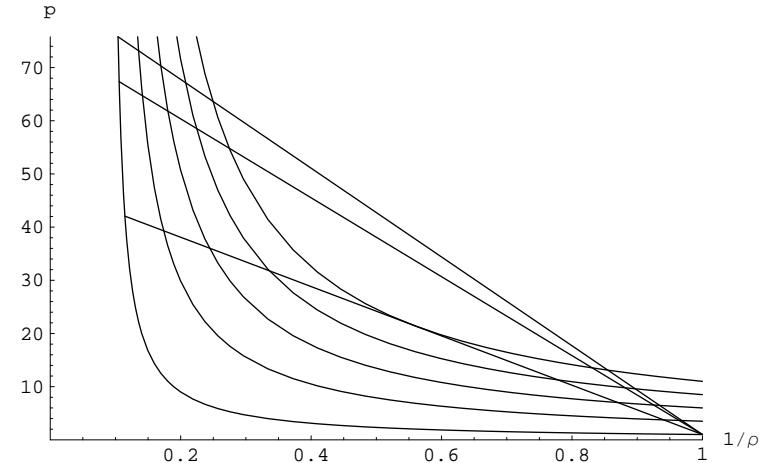
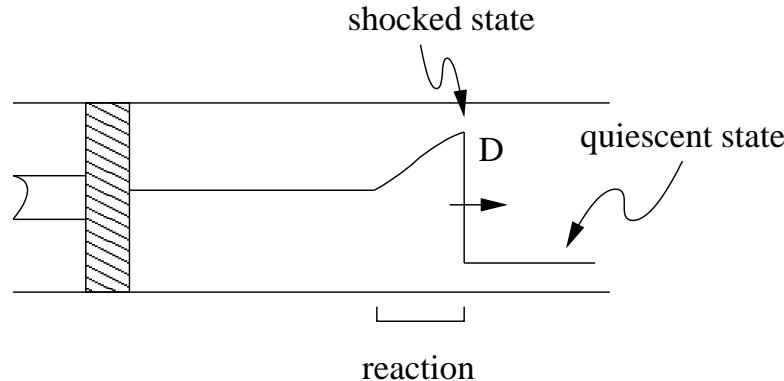
$$u^* = u^n + \Delta t \mathcal{L}(u^n),$$

$$u^{**} = \frac{3}{4}u^n + \frac{1}{4}u^* + \frac{1}{4}\Delta t \mathcal{L}(u^*),$$

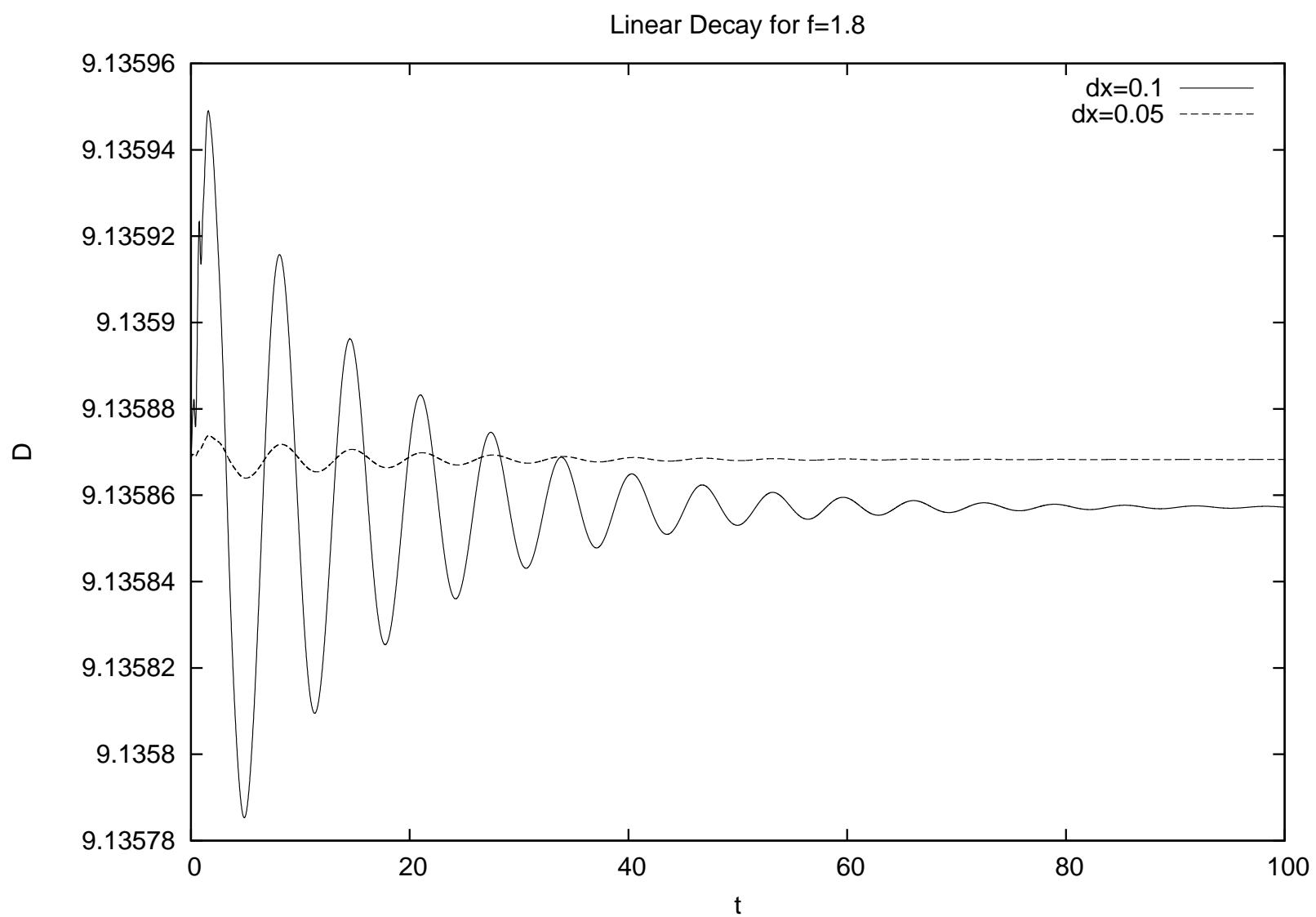
$$u^{n+1} = \frac{1}{3}u^n + \frac{2}{3}u^{**} + \frac{2}{3}\Delta t \mathcal{L}(u^{**}),$$

where  $\mathcal{L} = -\frac{\hat{f}_{j+1/2} - \hat{f}_{j+1/2}}{\Delta x}$ .

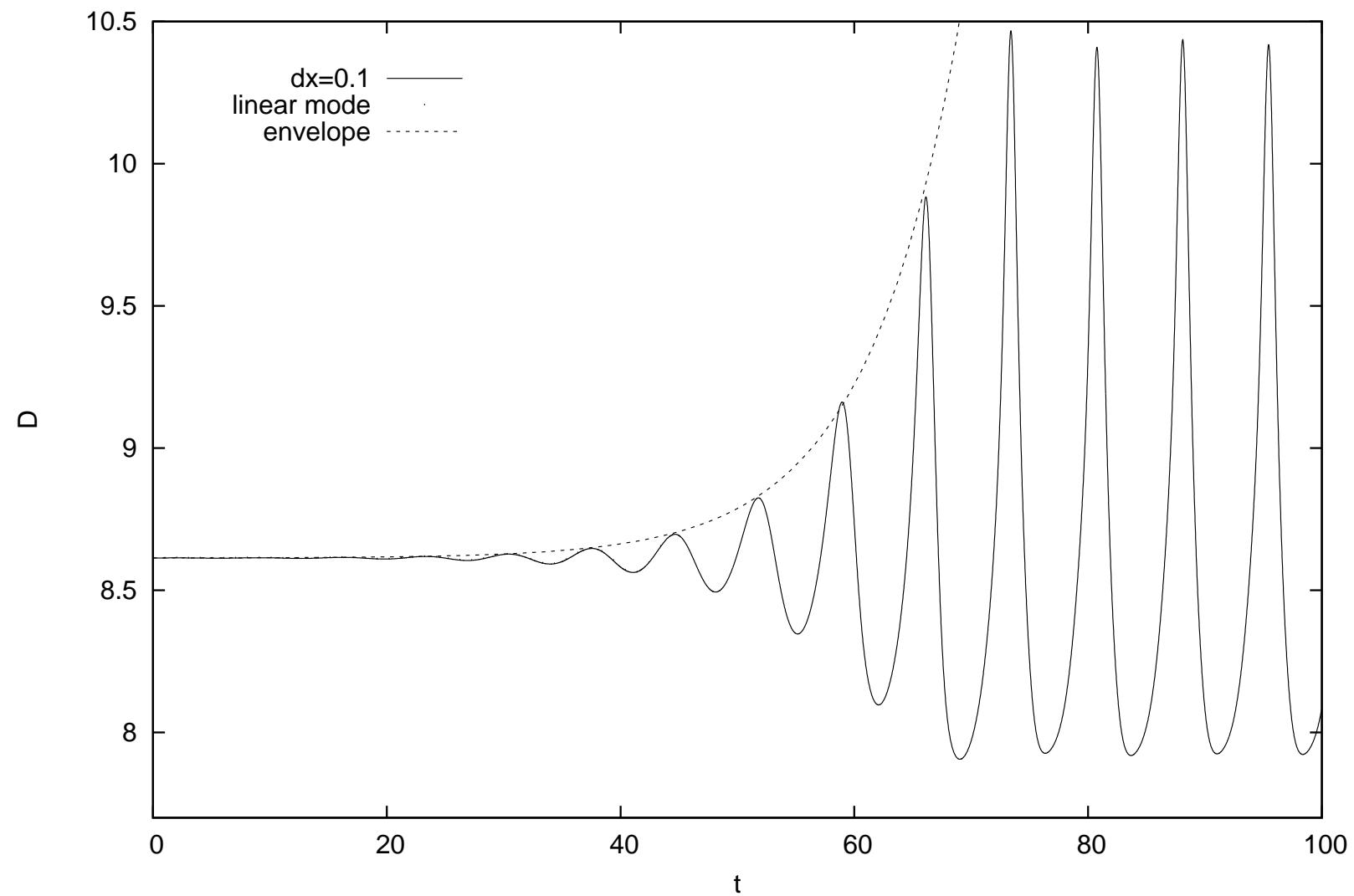
# ZND Structure Problem

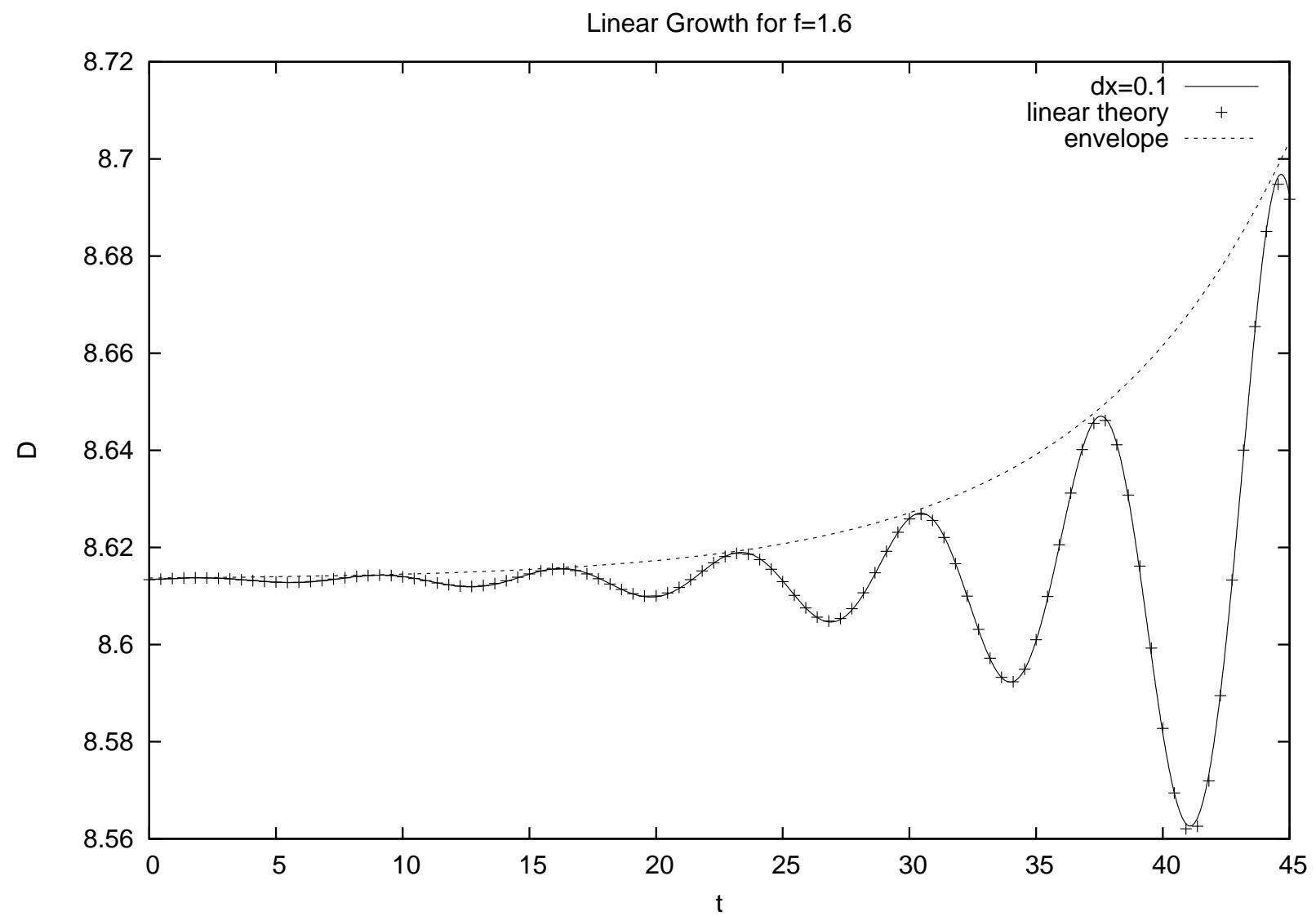


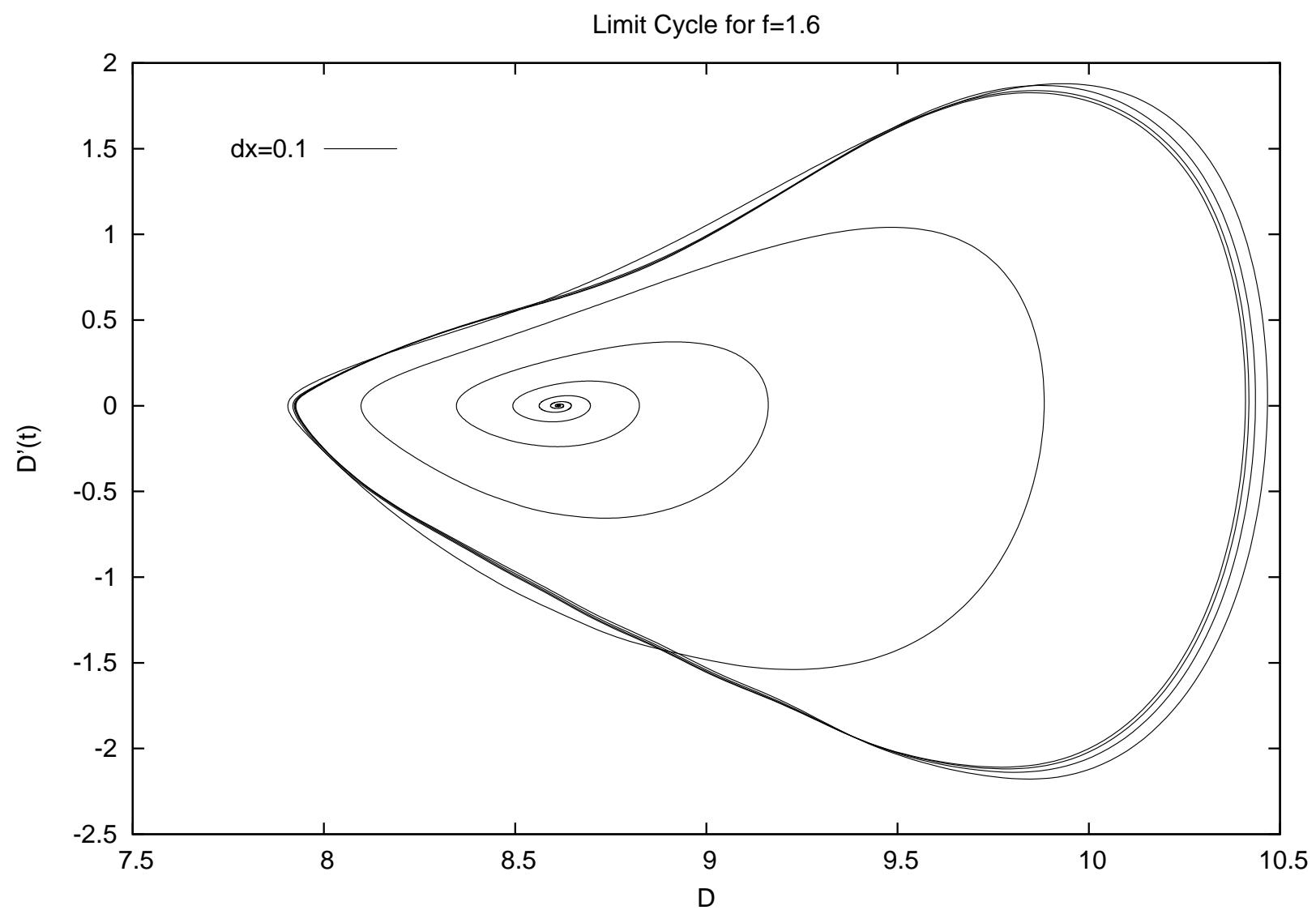
- parameters:  
 $E = 50, q = 50, \gamma = 1.2, D_{cj} = 6.80947$
- quiescent state:  $\rho = 1, u = 0, p = 1, \lambda = 0$
- consider  $f = (D/D_{cj})^2 = 1.8$  and  $1.6$



### Non-Linear Saturation for $f=1.6$







## Conclusions

- Shock fitting allows for highly accurate solutions containing a discontinuity.
- Validation of unstable mode for ZND problem from linear theory.
- Explicit stability bounds and convergence study presently lacking.
- 2-D extension needed for future work.