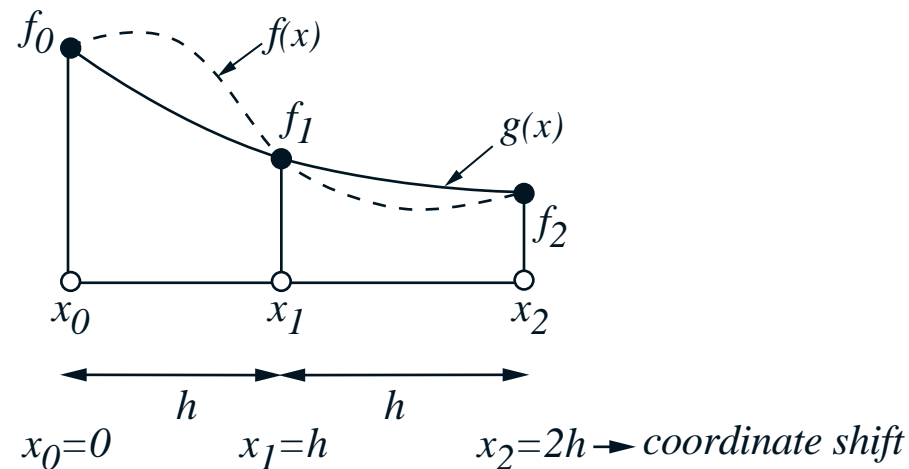


LECTURE 18

NUMERICAL INTEGRATION CONTINUED

Simpson's 1/3 Rule

- Simpson's 1/3 rule assumes 3 equispaced data/interpolation/integration points
- The integration rule is based on approximating $f(x)$ using *Lagrange quadratic* (second degree) interpolation.
- The sub-interval is defined as $[x_0, x_2]$ and the integration point to integration point spacing equals $h \equiv \frac{x_2 - x_0}{2}$



- Lagrange quadratic interpolation over the sub-interval:

$$g(x) = f_0 V_0(x) + f_1 V_1(x) + f_2 V_2(x)$$

where

$$V_0(x) = \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} \Rightarrow$$

$$V_0(x) = \frac{x^2 - 3hx + 2h^2}{2h^2}$$

$$V_1(x) = \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} \Rightarrow$$

$$V_1(x) = \frac{4hx - 2x^2}{2h^2}$$

$$V_2(x) = \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)} \Rightarrow$$

$$V_2(x) = \frac{x^2 - hx}{2h^2}$$

- Integration rule is obtained by integrating $g(x)$

$$I = \int_{x_o}^{x_2} f(x) \quad \Rightarrow \quad I = \int_{x_o}^{x_2} g(x)dx + E \quad \Rightarrow$$

$$I = \int_{x_o=0}^{x_2=2h} \left\{ f_o \left[\frac{x^2 - 3hx + 2h^2}{2h^2} \right] + f_1 \left[\frac{4hx - 2x^2}{2h^2} \right] + f_2 \left[\frac{x^2 - hx}{2h^2} \right] \right\} dx + E \quad \Rightarrow$$

$$I = \frac{1}{2h^2} \left[f_o \left(\frac{x^3}{3} - \frac{3hx^2}{2} + 2h^2x \right) + f_1 \left(\frac{4hx^2}{2} - \frac{2x^3}{3} \right) + f_2 \left(\frac{x^3}{3} - h\frac{x^2}{2} \right) \right]_0^{2h} + E \quad \Rightarrow$$

$$I = \frac{1}{2h^2} \left[f_o \left(8\frac{h^3}{3} - \frac{12h^3}{2} + 4h^3 - 0 \right) + f_1 \left(8h^3 - \frac{16}{3}h^3 \right) + f_2 \left(\frac{8h^3}{3} - h\frac{4h^2}{2} \right) \right] + E \quad \Rightarrow$$

- Simpson's 1/3 Rule

$$I = \frac{h}{3} [f_o + 4f_1 + f_2] + E$$

Evaluation of the Error for Simpson's 1/3 Rule

- Error is defined as:

$$E = I - \frac{h}{3}(f_o + 4f_1 + f_2) \Rightarrow$$

$$E = \int_0^{2h} f(x) dx - \frac{h}{3}(f_o + 4f_1 + f_2)$$

- We develop Taylor series expansions for $f(x)$, f_o , f_1 and f_2 about $x_1 = h$

$$f(x) = f_1 + (x-h) f_1^{(1)} + \frac{1}{2}(x-h)^2 f_1^{(2)} + \frac{1}{6}(x-h)^3 f_1^{(3)} + \frac{1}{24}(x-h)^4 f_1^{(4)} + O(x-h)^5$$

$$f_o = f_1 - h f_1^{(1)} + \frac{1}{2}h^2 f_1^{(2)} - \frac{h^3}{6} f_1^{(3)} + \frac{1}{24}h^4 f_1^{(4)} + O(h)^5$$

$$f_1 = f_1$$

$$f_2 = f_1 + h f_1^{(1)} + \frac{1}{2}h^2 f_1^{(2)} + \frac{h^3}{6} f_1^{(3)} + \frac{1}{24}h^4 f_1^{(4)} + O(h)^5$$

- Substituting into the expression for E

$$E = \int_0^{2h} \left(f_1 + (x-h) f_1^{(1)} + \frac{1}{2}(x-h)^2 f_1^{(2)} + \frac{1}{6}(x-h)^3 f_1^{(3)} + \frac{1}{24}(x-h)^4 f_1^{(4)} + O(x-h)^5 \right) dx$$

$$-\frac{h}{3} \left(f_1 - h f_1^{(1)} + \frac{1}{2}h^2 f_1^{(2)} - \frac{h^3}{6} f_1^{(3)} + \frac{1}{24}h^4 f_1^{(4)} + O(h)^5 + 4f_1 + f_1 + h f_1^{(1)} + \frac{1}{2}h^2 f_1^{(2)} + \frac{h^3}{6} f_1^{(3)} + \frac{1}{24}h^4 f_1^{(4)} + O(h)^5 \right)$$

\Rightarrow

$$E = (2h)f_1 + \frac{1}{2}(h^2 - h^2) f_1^{(1)} + \frac{1}{6}(h^3 + h^3)f_1^{(2)} + \frac{1}{24}(h^4 - h^4)f_1^{(3)}$$

$$+ \frac{1}{120}(h^5 + h^5)f_1^{(4)} + O(h)^6 - \frac{h}{3} \left[6f_1 + h^2 f_1^{(2)} + \frac{1}{12}h^4 f_1^{(4)} + O(h)^5 \right]$$

\Rightarrow

$$E = (2h - 2h)f_1 + \left(\frac{2}{6}h^3 - \frac{h^3}{3}\right)f_1^{(2)} + \left(\frac{h^5}{60} - \frac{h^5}{36}\right)f_1^{(4)} + O(h)^6$$

- Error for Simpson's 1/3 Rule

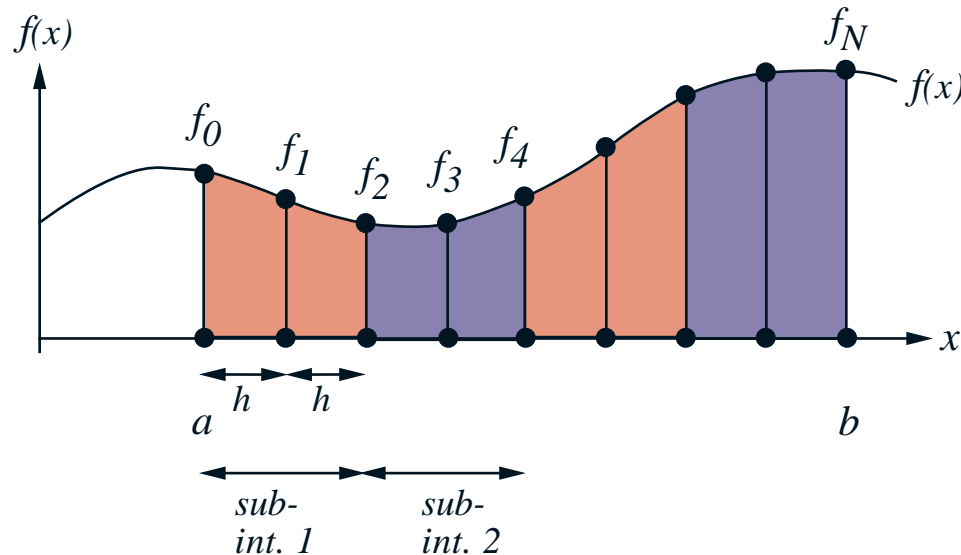
$$E = -\frac{1}{90}h^5 f_1^{(4)}$$

- This is the error for integration over one sub-interval of width $2h$!
 - Fifth order accurate.
 - Simpson's 1/3 Rule is exact for any cubic polynomial function
- We note that E can also be derived by
 - Estimating the error for Lagrange quadratic interpolation, $e(x) = f(x) - g(x)$, *in series form*
 - Integrating $e(x)$ over the integration interval $[x_0, x_2]$

$$E = \int_{x_0=0}^{x_2=2h} e(x) dx$$

Extended Simpson's 1/3 Rule

- Simply add up integrated values obtained using Simpson's 1/3 rule over each sub-interval.



- Sub-interval size = $2h$
- Number of sub-intervals = $\frac{N}{2}$
- Sub-interval width is $2h$ while the integration point to integration point spacing is equal to $h = \frac{b-a}{N}$

- Again we integrate over N points (the same as extended trapezoidal rule). Therefore

$$I = \int_a^b f(x) dx$$

\Rightarrow

$$I = \frac{h}{3}((f_0 + 4f_1 + f_2) + (f_2 + 4f_3 + f_4) + (f_4 + 4f_5 + f_6)$$

$$+ \dots + (f_{N-4} + 4f_{N-3} + f_{N-2}) + (f_{N-2} + 4f_{N-1} + f_N)) + E_{[a,b]}$$

\Rightarrow

$$I = \frac{h}{3}[f_0 + 4f_1 + 2f_2 + 4f_3 + 2f_4 + 4f_5 + \dots + 2f_{N-2} + 4f_{N-1} + f_N] + E_{[a,b]}$$

- In general we can write

$$I = \frac{h}{3} \left[f(a) + f(b) + 4 \sum_{i=1,2}^{N-1} f(a+ih) + 2 \sum_{i=2,2}^{N-2} f(a+ih) \right] + E_{[a,b]}$$

- Note that the total number of integration points $N + 1$ must be odd and therefore N must be even!
- The error term is also summed over the sub-intervals and each sub-interval term is evaluated at the mid node of the sub-interval.

$$E_{[a, b]} \approx \sum_{i=1}^{\frac{N}{2}} \left(-\frac{h^5}{90} f_{2i-1}^{(4)} \right)$$

$$\Rightarrow$$

$$E_{[a, b]} \approx -\frac{h^5}{90} \left(\frac{N}{2} \right) \left(\frac{2}{N} \sum_{i=1}^{\frac{N}{2}} f_{2i-1}^{(4)} \right)$$

$$\Rightarrow$$

$$E_{[a, b]} \approx -\frac{h^5}{90} \frac{N}{2} \overline{f^{(4)}}$$

where $\overline{f^{(4)}}$ = average of the 4th derivative over each sub-interval in the interval $[a, b]$.

- However we wish dependence on error to be expressed in terms of h , **not** in terms of the number of integration points.
- Noting that for the interval $[a, b]$

$$h = \frac{b-a}{N} \Rightarrow N = \frac{b-a}{h}$$

- Therefore

$$E_{[a,b]} = -\frac{h^5}{90} \cdot \frac{b-a}{h} \cdot \frac{1}{2} \overline{f^{(4)}}$$

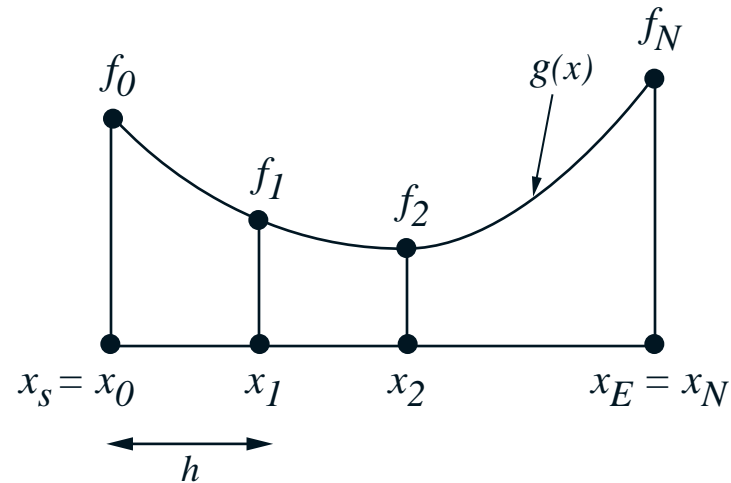
\Rightarrow

$$E_{[a,b]} \approx -\frac{h^4}{180} (b-a) \overline{f^{(4)}}$$

- Overall the error is 4th order

Newton Cotes Closed Formulae

- Derived by integrating Lagrange approximating polynomials (or equivalently Newton Interpolating formulae) using equispaced integration points (interpolating points, nodes, etc.) over the sub-interval defined by the interpolating data points



- The general form of Newton-Cotes closed formulae:

$$\int_{x_S}^{x_E} f(x) dx = \alpha h [w_0 f_0 + w_1 f_1 + w_2 f_2 + \dots + w_N f_N] + E$$

where

$$f_i = f(x_i) \quad x_i = x_S + ih \quad h \equiv \frac{x_N - x_0}{N}$$

- Closed formulae: The sub-interval is closed by the first and last integration points.

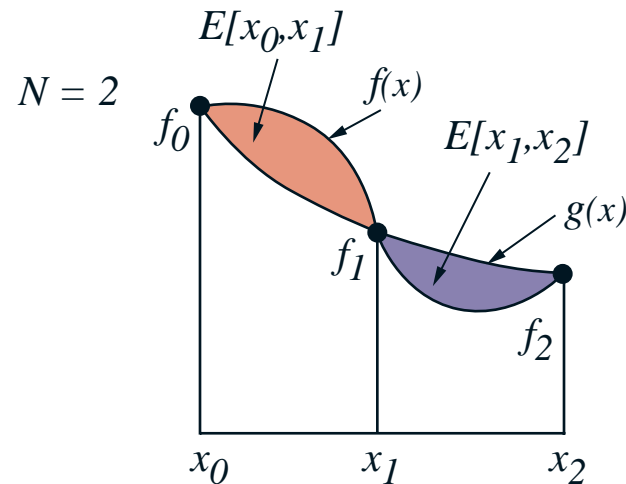
N	α	$w_i, i = 0, 1, 2, \dots, N$	E	<i>Note</i>
1	$\frac{1}{2}$	1 1	$-\frac{1}{12}h^3 f^{(2)}$	Trapezoidal Rule
2	$\frac{1}{3}$	1 4 1	$-\frac{1}{90}h^5 f^{(4)}$	Simpson's $\frac{1}{3}$ Rule
3	$\frac{3}{8}$	1 3 3 1	$-\frac{3}{80}h^5 f^{(4)}$	Simpson's $\frac{3}{8}$ Rule
4	$\frac{2}{45}$	7 32 12 32 7	$-\frac{8}{945}h^7 f^{(6)}$	
10	$\frac{5}{299376}$	16067 106300 -48525 272400 -260550 427368 -260550 272400 -48525 106300 16067	$-0.00412 h^{13} f^{(12)}$	Round off error tends to become a serious problem!

- Notes

- All these formulae integrate over one sub-interval only. They can be extended over $[a, b]$ simply by summing up integrals over each sub-interval.
- In addition the error is summed resulting in one less order of accuracy than the error over the individual sub-interval!
- Accuracy for Simpson's $\frac{3}{8}$ rule is very similar to accuracy of Simpson's $\frac{1}{3}$ rule.
- In general each formula will be *exact* for polynomials of one degree less than the order of the derivatives in the error terms.

N	$g(x)$	E	<i>Exact for</i>
1	linear	$\overline{f^{(2)}}$	linear
2	quadratic	$\overline{f^{(4)}}$	cubic
3	cubic	$\overline{f^{(4)}}$	cubic
4	quartic	$\overline{f^{(6)}}$	quintic

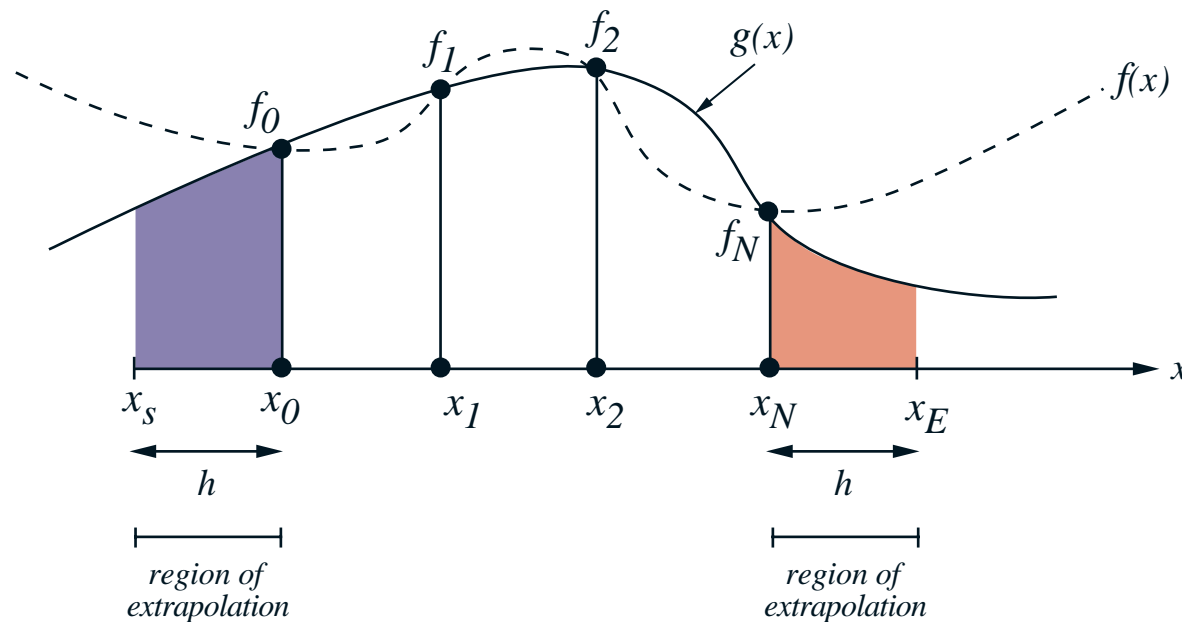
- It appears that for N even, the integration is exact for polynomials one degree greater than the interpolation function.
- For Simpson's 1/3 Rule:
 - It turns out that if $f(x)$ is a **cubic** and $g(x)$ is quadratic, $E_{[x_0, x_1]} = -E_{[x_1, x_2]}$



- The errors cancel over the interval **due to the location** of point x_1 !
- We can actually improve the accuracy of integration formulae by locating integration points in special locations!
- We do **not** experience any improvement in accuracy for $N = \text{odd}$.

Newton-Cotes Open Formulae

- Derived by integrating Lagrange approximating formulae (or equivalently Newton Interpolating formulae) using equispaced data points/nodes/integration points over the sub-interval defined by the interpolating data points **and** extended to the left and right by h .



- Note that $x_S = x_0 - h$ $x_E = x_N + h$ and $h = \frac{x_N - x_0}{N}$
- Note that $g(x)$ does not generally pass through $f(x_S)$ or through $f(x_E)$

- Newton Cotes open formula:

$$\int_{x_S}^{x_E} f(x) dx = \alpha h [w_0 f_0 + w_1 f_1 + \dots + w_N f_N] + E$$

N	α	$w_i \ i = 0, 1, \dots, N$	E	Error compared to closed interval	Interval size compared to closed interval
1	3/2	1 1	$\frac{1}{4}h^3 f^{(2)}$	3 ×	3 ×
2	4/3	2 -1 2	$\frac{28}{90}h^5 f^{(4)}$	28 ×	2 ×
3	5/24	11 1 1 11	$\frac{95}{144}h^5 f^{(4)}$	18 ×	1.7 ×

- Notes
 - Each formula and error is for *one* sub-interval with $N + 1$ data/node/integration points. We can extend the interval to $[a, b]$ by summing integrals and errors (error increases by one order).
 - Sub-interval errors are greater than closed formulae since
 - sub-interval is larger
 - the error in the interpolation functions tended to be greater near the ends and especially outside of the interpolating region!
 - Higher order formulae involve large coefficients with +/- signs. This leads to roundoff problems.
 - Open formulae can be used when functional values are not available at the integrating limits.