# THE ANATOMY OF A SINGULARITY

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## 1. Some basic facts

Denote by  $\mathcal{O} = \mathcal{O}_{N+1}$  the ring of germs of holomorphic functions  $f = f(z_0, \dots, z_N)$  defined in a neighborhood of  $\vec{0} \in \mathbb{C}^{N+1}$ . We denote by  $\mathfrak{m} \subset \mathcal{O}$  the maximal ideal of  $\mathcal{O}$ ,

$$f \in \mathfrak{m} \iff f(\vec{0}) = 0.$$

Let  $f \in \mathfrak{m}$ . Assume  $\vec{0}$  is an isolated critical point of f, i.e.  $\vec{0}$  is an isolated point of the variety

$$\partial_{z_i} f = 0, \quad \forall i = 0, \cdots, N.$$

We define the Jacobian ideal of f to be the ideal  $J_f \subset \mathcal{O}$  generated by  $\partial_{z_i} f$ ,  $i = 0, \dots, N$ . From the analytical Nullstellensatz we deduce

$$\sqrt{J_f} = \mathfrak{m} \iff \exists k > 0 : \mathfrak{m}^k \subset J_f \iff A_f := \dim_{\mathbb{C}} \mathfrak{O}/J_f < \infty.$$

The finite dimensional commutative  $\mathbb{C}$  -algebra  $A_f$  is called the local algebra of the critical point  $\vec{0}$  of f. Its dimension is called the *Milnor number* of f at  $\vec{0}$  and it is denoted by  $\mu = \mu(f, \vec{0})$ . It has a natural structure of  $\mathbb{C}\{t\}$ -algebra

$$t \cdot (g \mod J_f) = (fg) \mod J_F, \ \forall g \in \mathcal{O}$$

For every positive integer N we denote by  $j_N(f)$  the N-th jet of f. It can be identified with a polynomial of degree N in n + 1 complex variables.

Two germs  $f, g \in \mathfrak{m}$  are called *right-equivalent* and we write this  $f \sim_r g$  if g is obtained from g by a change in variables.

**Theorem 1.1** (Finite determinacy). (a) (Mather-Tougeron) Let  $f \in \mathfrak{m}$  have an isolated singularity at 0. Then

$$f \sim_r j_{\mu+1}(f)$$

(b) (Mather-Yau) Let  $f, g \in \mathfrak{m}$  have isolated singularities at 0. Then

 $f \sim_r g \iff A_f \cong A_g$  as  $\mathbb{C}\{t\}$  – algebras.

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**Example 1.2** (Brieskorn singularities). Consider three integers  $p, q, r \ge 2$  and consider the function

$$f = f_{p,q,r}(x, y, z) = az^p + by^q + cz^r.$$

Then  $\mu = (p-1)(q-1)(r-1)$ . The local algebra  $A_{p,q,r}$  is generated by the monomials  $e_{ijk} = x^i y^j z^k$  where  $0 \le i < p, \ 0 \le j < q, \ 0 \le k < r$ . We see that this algebra is isomorphic to the  $\mathbb{C}$ -group algebra of the Abelian group  $\mathbb{Z}/p \times \mathbb{Z}/q \times \mathbb{Z}/r$ . The singularity described by  $f_{2,2,n+1}$  is called the  $A_n$  singularity. It has Milnor number n.

**Example 1.3.** Consider the polynomial

$$D_4 = D_4(x, y, z) = x^2 y - y^3 + z^2$$

 $\vec{0}$  is an isolated critical point of  $D_4$ , the local algebra has dimension 4, and we can explicitly determine a basis

$$e_0 = 1, e_1 = x, e_2 = y, e_3 = y^2$$

It is easy to compute the multiplication table of the local algebra  $\mathcal{A}_{D_4} = \mathcal{O}_3/J_{D_4}$ .

	$e_1 = x$	$e_2 = y$	$e_3 = y^2$
$e_1 = x$	$3e_3$	0	0
$e_2 = y$	0	$e_3$	0
$e_3 = y^2$	0	0	0

Note that the  $D_4$ -singularity is weighted homogeneous. We recall that a function  $f = f(z_1, \dots, z_N)$  is called weighted homogeneous if there exist integers, i.e. there exists integers  $m_1, \dots, m_N, m$  such that

$$f(t^{m_1}z_1, t^{m_N}z_N) = t^m D_4(z_1, \cdots, z_N), \ \forall t \in \mathbb{C}^*.$$

The rational numbers  $w_i = m_i/m$  are called the *weights*. The weights of the  $D_4$  singularity are

$$w_1 = w_2 = \frac{1}{3}, \ w_3 = \frac{1}{2}.$$

A weighted homogeneous polynomial satisfies the *Euler identity* 

$$f = \sum_{i} w_i \frac{\partial f}{\partial z_i}.$$

Note that for such a function we have  $f \in J_f$  so the  $\mathbb{C}\{t\}$  module of  $A_f$  is very simple: t acts trivially.

## 2. The Milnor Fibration and the Gauss-Manin connection

Let  $f \in \mathfrak{m}$  have an isolated singularity at 0. Set  $\mu = \mu(f, 0)$ . According to Milnor, for  $\varepsilon > 0$  sufficiently small we can find an open neighborhood  $X = X_{\varepsilon}$  of  $0 \in \mathbb{C}^{N+1}$  so that  $f(X_{\varepsilon}) = \mathbb{D}_{\varepsilon} = \{|z| < \varepsilon\} \subset \mathbb{C}$  such that the induced map

$$f: X^* := X \setminus f^{-1}(0) \to \mathbb{D}_{\varepsilon}^*$$

is a local trivial fibration called the Milnor fibration. Its typical fiber  $X_f$  is smooth 2Ndimensional manifold with boundary called the Milnor fiber. Its boundary is a (2N - 1)manifold called the *link of the singularity*. The Milnor fiber which has the homotopy type of a wedge of  $\mu$  spheres of dimension N,

$$X_f \simeq \underbrace{S^N \lor \cdots \lor S^N}_{\mu}$$

The Milnor fibration defines a monodromy map

$$\mathfrak{M}_f: \pi_1(\mathbb{D}^*_{\varepsilon}) \to \operatorname{Aut}_{\mathbb{Z}}(H_N(X_f, \mathbb{Z})),$$

where  $H_{\bullet}$  denotes *reduced homology*. We denote by  $[\mathcal{M}_f]_{\mathbb{Z}}$  its  $\mathbb{Z}$ -conjugacy class and by  $[\mathcal{M}_f]_{\mathbb{C}}$  its  $\mathbb{C}$ -conjugacy class. The complex conjugacy class is completely determined by the complex Jordan normal form of  $\mathcal{M}_f$ .

**Theorem 2.1** (Monodromy Theorem, Griffith-Deligne). All the eigenvalues of  $\mathcal{M}_f$  are roots of 1 and its Jordan cells have dimension  $\leq (N+1)$ .

**Example 2.2.** (a) Consider the germ  $f : (\mathbb{C}, 0) \to (\mathbb{C}, 0), f(z) = z^n$ . Then the Milnor fiber  $f^{-1}$  can be identified with the group  $\mathfrak{R}_n$  of *n*-th roots of 1,

$$\mathfrak{R}_n = \{1, \rho, \cdots, \rho^{n-1}; \ \rho = e^{\frac{2\pi i}{n}} \}.$$

The Milnor number is (n-1). This is equal to the rank of the reduced homology  $\tilde{H}_0(f^{-1}(0),\mathbb{Z})$  which can be identified with the subgroup of the group algebra  $\mathbb{Z}[\mathfrak{R}_n]$ 

$$\widetilde{H}_0(f^{-1}(1), \mathbb{Z}) \cong \left\{ \sum_{k=0}^{n-1} a_k \rho^k \in \mathbb{Z}[\mathfrak{R}_n]; \ \sum_{k=0}^{n-1} a_k = 0 \right\}.$$

As basis in this group we can choose the "polynomials"

$$e_k := \rho^k - \rho^{k-1}, ; \ k = 1, \cdots, n-1.$$

Then

$$\mathcal{M}_f(e_k) = \begin{cases} e_{k+1} & \text{if } k < n-1 \\ -(e_1 + \dots + e_{n-1}) & \text{if } k = n-1 \end{cases}$$

We deduce  $\mathcal{M}_{A_{n-1}}^n = \mathbb{I}$ , i.e. all the eigenvalues of the monodromy are *n*-th roots of 1. (b) (Thom-Sebastiani) If  $f = f(x_1, \dots, x_p) \in \mathcal{O}_p$  and  $g = g(y_1, \dots, y_q) \in \mathcal{O}_q$  have isolated singularities at the origin, then so does  $f * g \in \mathcal{O}_{p+q}$ 

$$f * g(x, y) = f(x_1, \cdots, x_p) + g(y_1, \cdots, y_q)$$

and

$$X_{f*g} \simeq X_f * X_g :=$$
 the join of the Milnor fibers  $X_f$  and  $X_g$ 

(" $\simeq$ " denotes homotopy equivalence)

$$\mu(f * g, 0) = \mu(f, 0) \cdot \mu(g, 0), \quad [\mathcal{M}_{f * g}]_{\mathbb{C}} = [\mathcal{M}]_f \otimes [\mathcal{M}]_g$$

Note that if q = 1 and  $g(y) = y^2$  then

$$X_{f*y^2} \simeq \Sigma X_f,$$

where  $\Sigma$  denotes the suspension operation. The operation  $f \mapsto f * y^2$  is called *stabilization* and two singularities are called *stably equivalent* if they become right-equivalent after a finite number of stabilizations. Note that the singularity presented  $\{z^n = 0\}$  discussed in part (a) is stably equivalent to the  $A_{n-1}$ -singularity.

A theorem of J. Mather states that two hypersurface singularities  $\{f(x_1, \dots, x_p) = 0\}$  and  $\{g(y_1, \dots, y_q) = 0\}$  are stably equivalent if and only if their local algebras  $A_f$  and  $A_g$  are isomorphic as  $\mathbb{C}$ -algebras.

(c)  $\mathcal{M}_{D_4}$  was computed by Arnold. It is related to the Coxeter group with the same name. The Milnor fiber  $X_{D_4}$  is a 4-manifold with boundary and the intersection form q on  $\Lambda = H_2(X_{D_4}, \mathbb{Z})$  has a particularly nice form described in the Dynkin diagram below.



FIGURE 1. The Dynkin diagram  $D_4$ .

This means that  $\Lambda$  has a canonical integral basis consisting of vanishing spheres, i.e. embedded 2-spheres  $e_0, e_1, e_2, e_3$  with self intersection  $-2, q(e_\alpha, e_\alpha) = -2, \forall \alpha = 0, 1, 2, 3$ . Moreover

$$q(e_0, e_i) = 1, \ q(e_i, e_j) = 0, \ \forall i, j = 1, 2, 3.$$

A vanishing sphere  $e_{\alpha}$  determines an involution  $R_{\alpha}$  of  $\Lambda$ , the so called *Picard-Lefschetz* transformations associated to  $e_{\alpha}$ . More explicitly, it is the q-orthogonal reflection in the hyperplane q-orthogonal to  $e_{\alpha}$ , i.e.

$$R_{\alpha}(v) = v - 2\frac{q(v, e_{\alpha})}{q(e_{\alpha}, e_{\alpha})} = v + q(v, e_{\alpha}).$$

Then  $\mathcal{M}_{D_4}$  is conjugate (over  $\mathbb{Z}$ ) with the Coxeter transformation

$$T_{D_4} = R_0 R_1 R_2 R_3 \in \mathrm{GL}(\Lambda).$$

From the equality  $T_{D_4}^6 = \mathbb{I}$  (the Coxeter number of  $D_4$  is 6) we deduce that all the eigenvalues of  $\mathcal{M}_{D_4}$  are 6-th order roots of 1.

Using local trivializations in the Milnor fibration  $f: X^* \to \mathbb{D}^*$  we can parallel transport<sup>1</sup> cycles in a fiber  $X_t := f^{-1}(t) \cap X$  to nearby fibers and we obtain in this fashion the locally constant sheaf  $H_f$  whose stalk at  $t \in \mathbb{D}^*$  is  $\tilde{H}_N(X_t, \mathbb{Z})$ . It is called the sheaf of *vanishing cycles*. Its sections are families of vanishing cycles varying continuously from fiber to fiber. We will refer to these as *locally constant* vanishing cycles. We denote by  $\mathbb{Z}$  the constant sheaf on  $\mathbb{D}^*$  and we set

$$H^f := \underline{Hom}_{\mathbb{Z}}(H_f, \underline{\mathbb{Z}}),$$

where  $\underline{Hom}(\mathcal{F}, \mathcal{G})$  denotes the sheaf of morphisms between two sheaves  $\mathcal{F}, \mathcal{G}$ . Consider the sheaf  $\mathcal{E}$  of smooth complex valued functions on  $\mathbb{D}^*$ . The sheaf

$$\mathcal{H}^f := \underline{Hom}_{\mathbb{Z}}(H_f, \mathcal{E}) \cong H^f \otimes_{\mathbb{Z}} \mathcal{E}$$

is a locally free sheaf of  $\mathcal{E}$  modules and thus can be interpreted as the sheaf of sections of rank  $\mu$ -complex vector bundle over  $\mathbb{D}^*$  which we also denote by  $\mathcal{H}^f$ . It is called the *cohomological Milnor bundle*.

This bundle is equipped with a canonical holomorphic structure and a canonical flat connection  $\nabla$  constructed as follows.

<sup>&</sup>lt;sup>1</sup>This a  $C^{\infty}$  but not a holomorphic construction, as one may think. That is why the fact that the Gauss-Manin connection ends up having a holomorphic (even algebraic!) nature is somewhat surprising.

Given  $t_0 \in \mathbb{D}^*$ , a small contractible neighborhood U of  $t_0 \in \mathbb{D}_*$  and a  $\mathbb{Z}$ -basis  $\{e_1, \dots, e_{\mu}\}$ of vanishing cycles in  $X_t$ , we obtain by parallel transport a trivialization of  $H_f$  over U and then by duality a local frame  $(e^i)$  of  $\mathcal{H}^f |_U$ . Any  $s \in \Gamma(U, \mathcal{H}^f)$  can be written as  $s = \sum_k s_k e^k$ ,  $s_k = \langle s, e_k \rangle \in \mathcal{E}(U)$ . s is declared holomorphic if all the components  $s_k$  are holomorphic functions. We set

$$\nabla s := \sum_k (ds_k) \otimes e_k \in \Gamma(U, T^*U \otimes \mathcal{H}^f)$$

These notions are independent of the various choices.  $\nabla$  is called the *topological Gauss-Manin connection*. We denote by  $\mathcal{H}_{hol}^{f}$  the sheaf of holomorphic sections of  $\mathcal{H}^{f}$ .

Brieskorn has constructed free, coherent sheaves of  $\mathcal{O}_{\mathbb{D}}$ -modules  $\mathcal{L}_0, \mathcal{L}_1 \to \mathbb{D}$ , together with an *injective* morphisms of  $\mathcal{O}_{\mathbb{D}}$ -modules  $\varphi : \mathcal{L}_1 \hookrightarrow \mathcal{L}_0$  and *isomorphisms*  $\beta_i : \mathcal{H}^f \to \mathcal{L}_i |_{\mathbb{D}^*}, i = 0, 1$  such that over  $\mathbb{D}^*$  the diagram below is commutative



Moreover, if we denote by t the local coordinate on  $\mathbb{D}$  such that  $\mathcal{O}_{\mathbb{D},0} \cong \mathbb{C}\{t\}$  then there exists a natural isomorphisms of  $\mathbb{C}\{t\}$ -modules

$$\rho: \left(\mathcal{L}_0/\varphi(\mathcal{L}_1)\right)_0 \to A_f.$$

The sheaves  $\mathcal{L}_i$  are also known as the *Brieskorn lattices*. Each is an extension to  $\mathbb{D}$  of the coherent sheaf  $\mathcal{H}^f$ . Note also that the quotient  $\mathcal{L}_0/\varphi(\mathcal{L}_1)$  is a coherent sheaf supported at the center of  $\mathbb{D}$ .

We describe the restrictions to  $\mathbb{D}^*$  of the sheaves  $\mathcal{L}_i$  and the morphisms  $\varphi$ ,  $\beta_i^{-1}$ . Denote by  $\Omega^k$  sheaf of holomorphic k-forms on X, i.e. differential forms  $\omega$  locally described as

$$\omega = \sum_{\alpha} \omega_{\alpha} dz_{\alpha_1} \wedge \cdots dz_{\alpha_k}.$$

Given a small open disk  $U \subset \mathbb{D}^*$  we set  ${}^{f}U = f^{-1}(U)$  and

$$\mathcal{L}_1(U) \approx \Omega^N({}^{f}U) \, \operatorname{mod}\Big( \, d\Omega^{N-1}({}^{f}U) + df \wedge \Omega^{N-1}({}^{f}U) \, \Big).$$

We use the symbol " $\approx$ " instead of "=" since the above definition is only "morally correct".

The restriction of a holomorphic form  $\omega \in \Omega^N(U_f)$  to fiber  $X_t, t \in U$  is a closed form  $\omega_t$ and we denote by  $[\omega_t] \in H^N(X_t, \mathbb{C})$  the class it defines. This cohomology class depends only on the image of  $\omega \in \mathcal{L}_1(U)$ .

Given  $\omega \in \mathcal{L}_1(U)$  we obtain a holomorphic section<sup>2</sup>  $[\omega] \in \Gamma(U, \mathcal{H}^f)$  determined by the following rule: for every locally constant vanishing cycle  $U \ni t \mapsto c_t \in H_n(X_t, \mathbb{Z})$ 

$$\langle [\omega], c \rangle(t) = \int_{c_t} [\omega |_{X_t}].$$

The resulting map

$$\mathcal{L}_1|_{\mathbb{D}^*} \ni \omega \longmapsto [\omega] \ni \mathcal{H}^f_{hol}$$

is an isomorphism whose inverse is  $\beta_1$ .

<sup>&</sup>lt;sup>2</sup>The holomorphic nature of this section is by no means obvious since the cycle  $c_t$  only varies smoothly with t.

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The sheaf  $\mathcal{L}_0$  is intimately related to the notion of Poincaré residue. Given  $U \subset \mathbb{D}^*$  as above and  $\omega \in \Omega^{N+1}({}^{f}U)$ , we deduce from the fact that  $df \neq 0$  on  $X^*$  that  $\omega$  can be written as

$$\omega = df \wedge \eta, \ \eta \in \Omega^N_X({}^fU)$$

 $\eta$  is uniquely determined only modulo  $df \wedge \Omega^{N-1}({}^{f}U)$  and we denote by  $\frac{\omega}{df}$  the image of  $\eta$  in  $\Omega^{N} \mod df \wedge \Omega^{N-1}$ . Note that

$$\omega = df \wedge \eta = df \wedge \eta' \Longrightarrow \eta |_{X_t} = \eta' |_{X_t}, \ \forall t \in U.$$

Hence  $\frac{\omega}{df}$  defines on each fiber  $X_t$  a closed form  $\frac{\omega}{df}|_{X_t}$ . Its cohomology class does not change if we add to  $\omega$  forms of the type  $df \wedge d\eta$ ,  $\eta \in \Omega_X^{N-1}$  since  $\frac{df \wedge d\eta}{df} = d\eta$ . We get a map

$$\Omega^{N+1}({}^{f}U) \mod df \wedge d\Omega^{N-1}({}^{f}U) \to H^{N}(X_{t}, \mathbb{C}), \ \omega \longmapsto \Big[\frac{\omega}{df} \mid_{X_{t}}\Big].$$

The cohomology class  $\lfloor \frac{\omega}{df} \mid X_t \rfloor$  is called the *Poincaré residue of*  $\omega$  along  $X_t$ . We will denote it by  $\operatorname{Res}_f(\omega, X_t)$ . Now set

$$\mathcal{L}_0({}^fU) \approx \Omega^{N+1}({}^fU) \mod df \wedge d\Omega^{N-1}({}^fU).$$

For  $\omega \in \mathcal{L}_0({}^f U)$  we can integrate  $\operatorname{Res}_f(\omega, X_t)$  over locally constant vanishing cycles and obtain a holomorphic section  $\operatorname{Res}_f(\omega) \in \Gamma(U, \mathcal{H}^f)$ . Arnold refers to this section as the geometric section determined by the top dimensional form  $\omega$ . The resulting morphism of sheaves

$$\operatorname{\mathbf{Res}}_f: \mathcal{L}_0 |_{\mathbb{D}^*} \to \mathcal{H}^f_{hol}, \ \omega \mapsto \operatorname{\mathbf{Res}}_f(\omega)$$

is an isomorphism whose inverse is  $\beta_0$ . The map

$$\Omega^N \ni \omega \longmapsto df \wedge \omega \in \Omega^{N+1}$$

induces a morphism

$$\mathcal{L}_1 \approx \Omega^N \, \operatorname{mod} \left( \, df \wedge \Omega^{N-1} + d\Omega^{N-1} \, \right) \longrightarrow \Omega^{N+1} \, \operatorname{mod} \left( \, df \wedge d\Omega^{N-1} \, \right) = \mathcal{L}_0.$$

This is precisely the morphism  $\varphi$ .

The exterior differentiation  $d: \Omega^N \to \Omega^{N+1}$  induces a morphism of sheaves

$$d: \mathcal{L}_1 \mid_{\mathbb{D}^*} \to \mathcal{L}_0 \mid_{\mathbb{D}^*} .$$

This is intimately related to the (topological) Gauss-Manin connection.

**Theorem 2.3** (Gelfand-Leray formula). The following diagram of sheaves and morphisms of sheaves is commutative

$$\begin{array}{c} \mathcal{L}_1 |_{\mathbb{D}^*} \xrightarrow{d} \mathcal{L}_0 |_{\mathbb{D}^*} \\ & & & \\ \beta_1 \\ & & & \\ \beta_1 \\ & & \\ \mathcal{H}^f \xrightarrow{\nabla_t} \mathcal{H}^f \end{array}$$

Hence if we start with  $\omega \in \Omega^n({}^fU)$  we obtain a section  $[\omega] \in \Gamma(U, \mathcal{H}^f_{hol})$  and for every locally constant vanishing cycle  $t \mapsto c_t$  we have

$$\frac{d}{dt}\int_{c_t} [\omega] = \int_{c_t} \left[\frac{d\omega}{df}\right].$$

Suppose  $S = S_{\theta} \subset \mathbb{D}^*$  is an angular sector

$$S = \{t \in \mathbb{D}^* \mid \arg t \mid \le \theta \}, \ \theta \in (0, \pi).$$

We fix a branch of log t on U such that log 1 = 0 and for every real number  $\alpha$  we set  $t^{\alpha} = e^{\alpha \log t}$ . Define

 $\Lambda^f := \{ r \in \mathbb{R}; \ \exp(2\pi \mathbf{i} r) \text{ is an eigenvalue of the monodromy } \mathcal{M}_f \},\$ 

and  $\Lambda^f_{\nu} = \Lambda^f \cap (\nu, \infty)$ ,  $\forall \nu \in \mathbb{R}$ . From the monodromy theorem we deduce that  $\Lambda^f$  consists of finitely many arithmetic progression of rational numbers. We have the following fundamental result.

**Theorem 2.4** (Regularity Theorem, Deligne-Griffiths). Denote by  $j = j_f$  the largest dimension of the Jordan cells of  $\mathcal{M}_f$ . Suppose  $\omega \in \Omega^{N+1}(X)$  and  $S_\theta \ni t \stackrel{c}{\longmapsto} c_t$  is a parallel vanishing cycle. Then there exists a real number  $\nu$  and for every  $\alpha \in \Lambda^f_{\nu}$  a polynomial  $P_{\alpha} = P_{\alpha,\omega,c} \in \mathbb{C}[s]$  of degree  $\langle j \text{ such as } t \to 0 \text{ in } S$  we have the asymptotic expansion

$$\int_{c_t} [\operatorname{\mathbf{Res}}_f \omega] \sim \sum_{r \in \Lambda^f_{\nu}} t^{\alpha} P_{\alpha}(\log t).$$

Remark 2.5. Let  $\omega \in \Omega^{N+1}(X)$ . We can write  $\omega = gd\vec{z}$ , where  $d\vec{z} = dz_0 \wedge \cdots \wedge dz_N$  and g is a holomorphic function on X. Since 0 is an isolated critical point of f we deduce from the analytical Nullstellensatz that there exists an integer  $\ell > 0$  such that

$$f^{\ell} \in \mathfrak{m}^{\ell} \subset J_f.$$

In other words, there exist an open neighborhood V of 0 in X and holomorphic functions  $a^0, \dots, a^n$  on V such that

$$f^{\ell} = \sum_{k} a^{k} \partial_{z_{k}} f \quad \text{on } V.$$

If we denote by A the vector field  $A = \sum_k a^k \partial_{z_k}$  and we denote by  $\iota_A$  the contraction by A then we can rewrite the above equality as

$$f^{\ell}d\vec{z} = df \wedge \iota_A d\vec{z}.$$

In particular, we deduce that on  $V^* - V \setminus f^{-1}(0)$  we have the equality

$$gdV = f^{-\ell}gdf \wedge \iota_A d\vec{z} \Longleftrightarrow \frac{\omega}{df} = f^{-\ell}\iota_A\omega.$$

We can assume V has the form  $V = f^{-1}(\mathbb{D}_{\varepsilon}) \cap X$ . Now observe that  $\iota_A \omega$  defines a section

$$[g\iota_A\omega] \in \Gamma(\mathbb{D}^*_{\varepsilon}, \mathcal{L}_1) \text{ and } [f^{-\ell}\iota_A\omega] = t^{-\ell}[\iota_A\omega] \in \Gamma(\mathbb{D}^*_{\varepsilon}, \mathcal{L}_1).$$

We have

$$\int_{c_t} \operatorname{Res}_f(\omega) = t^{-\ell} \int_{c_t} [\iota_A \omega], \quad \forall 0 < |t| \ll 1.$$

This shows that we can expect these integrals will "explode" as  $t \to 0$  so we can expect that the real number  $\nu$  in the regularity theorem is < 0.

On the other hand, according to Malgrange, the polynomial  $P_{\alpha}(s) \equiv 0$  if  $\alpha \leq -1$  so that in the above theorem we can assume  $\nu = -1$ . Thus these integrals explode but slower than  $t^{-1}$ .

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### 3. The spectrum of a singularity

Suppose  $(e_1, \dots, e_{\mu})$  is a basis of vanishing cycles in  $X_{t_0}$  for some  $t_0$ . We can extend them by parallel transport over U to a trivialization  $H_f|_U$ . For every holomorphic function g on X we obtain  $\mu$  asymptotic expansions

$$I_{\omega_g, e_k}(t) := \int_{e_k(t)} \operatorname{Res}_f(\omega_g) \sim \sum_{\alpha \in \Lambda_{-1}^f} t^{\alpha} P_{\alpha, \omega, k}(\log t), \ \omega_g = g dz^0 \wedge \dots \wedge dz^n.$$

We set

 $\nu_k(\omega) = \min\{\alpha \in \Lambda_{-1}^f; \ P_{\alpha,\omega,k} \neq 0\}$ 

and we define the *order* of the geometric section  $s_g = \operatorname{Res}(\omega_g)$  to be

$$\nu = \nu(\omega_g) = \min\{\nu_k(\omega); \ k = 1, \cdots, \mu\}.$$

If we denote by  $(e^k)$  the basis if  $H^f|_U$  dual to  $(e_i)$  then we set

$$s_{max}(\omega_g) = \sum_{k=1}^{\mu} t^{\nu} P_{\nu,\omega_g,k}(\log t) e^k \in \Gamma(U, \mathcal{H}^f_{hol}).$$

This section is independent of the basis  $(e_i)$  and moreover, it extends to a section of  $\mathcal{H}_{hol}^f$ over the entire punctured disk  $\mathbb{D}^*$ . It is called the *principal part* of the geometric section  $\operatorname{\mathbf{Res}}_f(\omega)$ .

**Example 3.1.** Consider the function  $f: X = \mathbb{C} \to \mathbb{C}, z \mapsto t = z^n$ . Let  $\zeta := e^{\frac{2\pi i}{n}}$ . For every  $t = \rho e^{i\theta}$  in the sector  $S = S_{\pi/2} = \{ \operatorname{\mathbf{Re}} z > 0 \}$  we set

$$t^{1/n} = \rho^{1/n} e^{\frac{i\theta}{n}}, \quad e_k(t) = t^{1/n} \left(\zeta^k - \zeta^{(k-1)}\right) \in \tilde{H}_0(f^{-1}(t), \mathbb{Z}), \quad k = 1, \cdots, n-1.$$

For  $1 \le m < n$  we set  $\omega_m = z^{m-1} dz = \frac{1}{m} d(z^m) \in \Omega^1(X)$ . Then

$$\frac{\omega_m}{df} = \frac{z^{m-1}dz}{nz^{n-1}dz} = \frac{1}{n}z^{m-n} \in \Omega^0(X^*).$$

For  $t \in S$  we have

$$\int_{e_k(t)} \frac{\omega_m}{df} = \frac{1}{n} \left( (t^{1/n} \zeta^k)^{(m-n)} - (t^{1/n} \zeta^{k-1})^{(m-n)} \right) = \frac{1}{n} (\zeta^{km}) t^{\frac{(m-n)}{n}} \left( 1 - \zeta^{-m} \right).$$

We conclude that

$$\nu(\omega_m) = \frac{m}{n} - 1 < 0, \ 1 \le m < n.$$

Returning to the general case, let us make the change in variables  $t = e^s$ ,  $\operatorname{Re} s < 0$  and we (ambiguously) set  $e_k(s) = e_k(e^s)$ . Fix  $t_0 \in \mathbb{D}^*$ ,  $\operatorname{Im} t_0 = 0$  and  $s_0 = \log t_0 \in \mathbb{R}$ . Set

$$\underline{\mathbf{e}}(s) = \begin{bmatrix} e_1(s), \cdots, e_{\mu}(s) \end{bmatrix}, \quad \overline{\mathbf{e}}(s) = \begin{bmatrix} e^1(s) \\ \vdots \\ e^{\mu}(s) \end{bmatrix}.$$

In the basis ( $\underline{\mathbf{e}}(s_0)$ ) the monodromy  $\mathcal{M}_f$  is represented by a  $\mu \times \mu$  matrix  $M = (m_j^i)_{1 \le i,j \le \mu}$ and we have the equalities

$$\underline{\mathbf{e}}(s_0 + 2\pi \mathbf{i}) = \underline{\mathbf{e}}(s_0) \cdot M \iff e_i(s_0 + 2\pi \mathbf{i}) = \sum_j m_i^j e_j(s_0)$$

$$\bar{\mathbf{e}}(s_0) = M \cdot \bar{\mathbf{e}}(s_0 + 2\pi \mathbf{i}) \Longleftrightarrow e^i(s_0) = \sum_j m^i_j e^j(s_0 + 2\pi \mathbf{i})$$

Given  $\omega \in \Omega^{N+1}(X)$  we define the row vector

$$\vec{I}_{\omega} = [I_{\omega,1}(s), \cdots, I_{\omega,\mu}(s)], \quad I_{\omega,k} = \int_{e_k(s)} \operatorname{Res}_f \omega.$$

Note that

$$\vec{I}_{\omega}(s+2\pi \mathbf{i}) = \vec{I}_{\omega}(s) \cdot M.$$

If we pick  $\mu$ -forms  $\omega_1, \dots, \omega_\mu \in \Omega^{n+1}(X)$  we can form the  $\mu \times \mu$  period matrix

$$P(s) = \begin{bmatrix} \vec{I}_{\omega_1}(s) \\ \vdots \\ \vec{I}_{\omega_\mu}(s) \end{bmatrix}.$$

It satisfies

$$P(s+2\pi \mathbf{i}) = P(s) \cdot M.$$

Since  $M \in \operatorname{GL}_{\mu}(\mathbb{Z})$  we deduce that

$$\det P(s + 2\pi \mathbf{i}) = \pm \det P(s).$$

Thus det  $P(s)^2$  is a well defined meromorphic function  $t \mapsto \delta(t; \omega_1, \dots, \omega_\mu)$  on  $\mathbb{D}$  with a possible pole at t = 0. We denote by  $\nu(\omega_1, \dots, \omega_\mu) \in \frac{1}{2}\mathbb{Z}$  its order at t = 0 divided by 2.

Theorem 3.2 (Varchenko).

$$u(\omega_1, \cdots, \omega_\mu) \ge \max\left\{\frac{N-1}{2}\mu, \sum_{j=1}^{\mu}\nu(\omega_j)\right\}$$

with equality for a generic choice of  $\{\omega_1, \dots, \omega_\mu\}$ . In such a generic case we also have the equality

$$\nu(\omega_1, \cdots, \omega_\mu) = \frac{N-1}{2}\mu = \sum_{j=1}^{\mu} \nu(\omega_j)$$

We will refer to such a generic choice as a  $\mathbb{C}\{t\}$ -basis and we will use the notation  $\underline{\omega}$  to denote an ordered  $\mathbb{C}\{t\}$ -basis.

We define a *rational divisor* on  $\mathbb{R}$  to be a finite formal linear combination of the form

$$\sum_{q \in \mathbb{Q}} n_q \cdot (q), \quad n_q \in \mathbb{Z}, \quad n_q = 0 \text{ for all but finitely may } q\text{'s.}$$

In other words, a rational divisor is an element

$$\mathbb{Z}^{(\mathbb{Q})} =$$
functions  $f : \mathbb{Q} \to \mathbb{Z}$  with finite support.

For a rational number q we denote by  $(q) \in \mathbb{Z}^{(\mathbb{Q})}$  the Dirac function supported at q. For any function  $f : \mathbb{Q} \to \mathbb{Q}$  with finite fibers and any divisor  $D \in \mathbb{Z}^{(\mathbb{Q})}$  we define

$$f^*D = \sum_{r \in \mathbb{Q}} n_{f(r)}(f(r)) = \sum_{q \in \mathbb{Q}} \sum_{f(r)=q} n_q(q).$$

A divisor will be called invariant with respect to f if  $D = f^*D$ .

Given a  $\mathbb{C}{t}$ -basis  $\underline{\omega} = (\omega_1, \cdots, \omega_1)$  we set

$$(\underline{\omega}) = \sum_{i=1}^{\mu} (\nu(\omega_i)).$$

Following Steenbrink and Varchenko, we define for every  $\alpha \in \Lambda^f$  the subsheaf  $S_{\alpha}$  of  $\mathcal{H}_{hol}^f$ spanned over  $\mathcal{O}_{\mathbb{D}^*}$  by the principal parts of the geometric sections of order  $\alpha$ . One can show that each of them is a locally free sheaf and defines a sub-bundle of  $\mathcal{H}^f$ . The multiplication by t defines an inclusion

$$\mathbb{S}_{\alpha-1} \hookrightarrow \mathbb{S}_{\alpha}.$$

Note that  $S_{\alpha} = 0$  for all  $\alpha \leq -1$ . It is a highly nontrivial fact that  $S_N = \mathcal{H}_{hol}^f$ .

The spectrum of f is the divisor sp  $(f) \in \mathbb{Z}^{(\mathbb{Q})}$  defined by

$$\operatorname{sp}(f) = \sum_{\alpha \in \Lambda_{-1}^{f}} \left( \dim_{\mathbb{C}} \mathfrak{S}_{\alpha}/t \cdot \mathfrak{S}_{\alpha-1} \right) \cdot (\alpha).$$

If we write

$$\operatorname{sp}(f) = \sum_{\alpha \in \Lambda_{-1}^f} n_{\alpha} \cdot (\alpha)$$

then the numbers  $\alpha$  such that  $n_{\alpha} \neq 0$  are called the *spectral numbers of* f. The integer  $n_{\alpha}$  is called the multiplicity of  $\alpha$  (in the spectrum of f). Since  $S_N = \mathcal{H}_{hol}^f$  we deduce

$$n_{\alpha} = 0, \quad \forall \alpha \ge N.$$

**Theorem 3.3** (Varchenko). Suppose  $f = f(z_0, \dots, z_N) \in \mathcal{O}_{N+1}$ . Then the spectrum  $\operatorname{sp}(f)$  is well defined, i.e. it is indeed a rational divisor supported inside the interval (-1, N). Moreover, for any  $\mathbb{C}\{t\}$ -basis  $\underline{\omega}$  of f we have the equality

$$\operatorname{sp}(f) = (\underline{\omega})$$

and  $\operatorname{sp}(f)$  is invariant with respect to the reflection in the midpoint of [-1, N].

To every divisor  $D = \sum_q n_q(q) \in \mathbb{Z}^{(\mathbb{Q})}$  we associate the Laurent-Puiseux polynomial

$$S_D(T) = \sum_q n_q T^q.$$

Note that the polynomial  $S_D$  completely determines the divisor D. When D = sp(f) we set

$$S_f(T) := S_{\operatorname{sp}(f)}(T).$$

We will refer to  $S_f(T)$  as the spectral polynomial of f.

Theorem 3.4 (Varchenko).

$$S_{f*g}(T) = T \cdot S_f(T) \cdot S_f(T).$$

Remark 3.5. If, following Saito, we define

$$S_f(T) = TS_f(T)$$

then the last equality has the more natural form

$$\tilde{S}_{f*g}(T) = \tilde{S}_f(T) \cdot \tilde{S}_g(T).$$

**Example 3.6.** Consider again the function  $f(z) = z^n$  discussed in Example 3.1 so that

$$N = 0, \ \mu = n - 1, \ \frac{N - 1}{2}\mu = -\frac{n - 1}{2}.$$

Then the period matrix is given by

$$P_k^m(t) = \int_{e_k(t)} \omega_m = \frac{1}{n} (\zeta^{km}) t^{\frac{(m-n)}{n}} (1 - \zeta^{-m}).$$

and we have

$$\det P(t) = \frac{1}{n^{n-1}} \left( \prod_{m=1}^{n-1} t^{\frac{(m-n)}{n}} \left( 1 - \zeta^{-m} \right) \right) \cdot \det[\zeta^{km}]_{1 \le k, m \le n-1}.$$

The last determinant is a Vandermonde determinant and it is non zero. Hence the order of det P(t) at zero is

$$\sum_{m=1}^{n-1} \left(\frac{m}{n} - 1\right) = -\frac{n-1}{2} = \frac{N-1}{2}\mu$$

Thus the collection  $\{z^m dz\}_{1 \le m \le n-1}$  is a basis and we deduce

$$S_{z^n}(T) = \sum_{m=1}^{n-1} T^{\frac{m}{n}-1} = T^{-1} \sum_{m=1}^{n-1} T^{m/n} = T^{-1} \frac{T^{\frac{1}{n}} - T}{1 - T^{\frac{1}{n}}}$$

Using Theorem 3.4 we deduce that for a Brieskorn singularity  $f_{a_0,\dots,a_N} = z_0^{a_0} + \dots + z_N^{a_N}$  we have

$$S_{f_{a_0,\dots,a_N}}(T) = T^{-1} \prod_{j=0}^N \frac{T^{1/a_j} - T}{1 - T^{1/a_j}}$$

More generally, if f is a quasihomogeneous function with weights  $w_0, \dots, w_N$  then

$$S_f = T^{-1} \prod_{j=0}^N \frac{T^{w_j} - T}{1 - T^{w_j}}.$$

In particular, the  $D_4$  singularity is quasihomogeneous with weights (1/3, /1/3, 1/2) and we have

$$S_{D_4}(T) = T^{-1} \left( \frac{T^{1/3} - T}{1 - T^{1/3}} \right)^2 \frac{T^{1/2} - T}{1 - T^{1/2}} = T^{1/6} (1 + T^{1/3})^2 = T^{1/6} + 2T^{1/2} + T^{5/6}.$$

The geometric genus of the isolated singularity defined by  $f \in \mathcal{O}_{N+1}$  is the number of nonpositive spectral numbers of f counted with their multiplicities. In terms of a  $\mathbb{C}\{t\}$ -basis  $\underline{\omega} = \{\omega_1, \dots, \omega_\mu\}$  of f, the geometric genus is the number of  $\omega_j$ 's with the property that there exists a locally constant vanishing cycle  $c_t$  such that the integral of  $\omega_j$  along  $c_t$  does not converge to zero as  $t \to 0$  inside an angular sector. We denote the geometric genus by  $p_q(f, 0)$ . For example  $p_q(z^n, 0) = n - 1$ ,  $p_q(D_4, 0) = 0$ .

For generic f's the geometric genus can be given a combinatorial description, similar in spirit to the above description of  $p_q(z^n, 0)$ .

Let  $f = f(z_0, \dots, z_N)$ . Set  $L := \mathbb{Z}^{N+1}$ ,  $L^+ := \mathbb{Z}_{\geq 0}^{n+1}$ ,  $L_{\mathbb{R}} = L \otimes \mathbb{R}$ . For  $\alpha \in L$  we set  $\overline{z}^{\alpha} := z_0^{\alpha_0} \cdots z_N^{\alpha_N}$ . We can write

$$f = \sum_{\alpha \in L^+} f_\alpha \vec{z}^\alpha$$

We set

$$\operatorname{supp} f = \{ \alpha \in L_+; \ f_\alpha \neq 0 \}.$$

The (local) Newton polyhedron of f, denoted by  $\Gamma_+(f)$  is the convex hull of  $\operatorname{supp}(f) + L^+$ . The germ f is called *convenient* if its Newton polyhedron intersects all the coordinate axes of  $L_{\mathbb{R}}$ . Equivalently, this means that for every  $j = 0, \dots, N$ , there exists  $n_j \in \mathbb{N}$  such that the monomial  $z_n^{n_j}$  enters into the Taylor expansion of f. We can assume without a loss of generality that f is a convenient polynomial. Indeed, according to Mather-Tougeron theorem, the analytic type of the singularity described by f does not change if we modify arbitrarily the terms in the Taylor expression of degree  $> \mu + 1$ . In particular, we can replace f by  $j_{\mu+1}(f) + \sum_{j=0}^{N} z_j^{\mu+2}$  and not change the analytic type of the singularity. The Newton polyhedron is the intersection of finitely many half-spaces. Its boundary has

The Newton polyhedron is the intersection of finitely many half-spaces. Its boundary has compact and noncompact faces. The Newton diagram of f, denoted by  $\Delta(f)$ , is the union of all the compact faces. These are compact polyhedra of dimensions  $\leq N$ . For each face  $\gamma$  of the Newton diagram we set

$$f_{\gamma} = \sum_{\alpha \in \gamma} f_{\alpha} \vec{z}^{\alpha}.$$

The polynomial f is called *Newton nondegenerate* if for every face  $\gamma$  of  $\Delta(f)$  the polynomials

$$\frac{\partial f_{\gamma}}{\partial z_j}, \ j = 0, 1, \cdots, N$$

have no common zero on  $(\mathbb{C}^*)^{N+1}$ . This condition is generic in the space of convenient polynomials with a fixed Newton polyhedron.

Let  $\vec{w}_0 = (1, \dots, 1)$ . A monomial  $\vec{z}^{\alpha}$  is called *subdiagramatic* if  $\alpha + \vec{w}_0$  does not lie in the interior of the Newton polyhedron.

**Theorem 3.7** (Khovanski-Varchenko-Saito). Suppose  $f \in \mathcal{O}_{N+1}$  is a Newton nondegenerate convenient polynomial. Then  $p_g(f, 0)$  is equal to the number of subdiagramatic monomials.

**Example 3.8.** Consider the singularity  $D_4$ . The defining polynomial  $x^2y - y^3 + z^2$  is not convenient, but near 0 it is right equivalent to  $cx^6 + x^2y - y^3 + z^2$ , where c is a complex number. The Newton diagram of this polynomial is depicted in Figure 2. It consists of 0- dimensional, 1-dimensional and 2-dimensional faces. The 2-dimensional faces are the triangles ACD and BCD. The 1-dimensional faces are the edges of these triangles and the 0-dimensional faces are the vertices of these triangles. We have

$$f_{ACD} = cx^{6} + x^{2}y + z^{2}, \quad \frac{\partial f_{ACD}}{\partial x} = 6cx^{5} + xy, \quad \frac{\partial f_{ACD}}{\partial y} = x^{2}, \quad \frac{\partial f_{ACD}}{\partial z} = 2z.$$
$$f_{BCD} = y^{3} + x^{2}y + z^{2}, \quad \frac{\partial f_{BCD}}{\partial x} = 2xy, \quad \frac{\partial f_{BCD}}{\partial y} = 3y^{2} + x^{2}, \quad \frac{\partial f_{BCD}}{\partial z} = 2z.$$



FIGURE 2. The Newton diagram of  $cx^6 + x^2y - y^3 + z^2$ .

etc. One can check that for  $c \neq 0$  this is Newton nondegenerate. The two top dimensional faces of the Newton diagram are contained in the planes

$$ACD \subset \left\{\underbrace{\frac{1}{6}x + \frac{2}{3}y + \frac{1}{2}z}_{:=\ell_1(x,y,z)=1}\right\}, \quad BCD \subset \left\{\underbrace{\frac{1}{3}x + \frac{1}{3}y + \frac{1}{2}z}_{:=\ell_2(x,y,z)}=1\right\}$$

the Newton polyhedron is defined by

$$\ell_1(x, y, z) \ge 1$$
 and  $\ell_2(x, y, z) \ge 1$ .

A subdiagramatic monomial  $x^m y^n z^p$  satisfies

$$\ell_1(m, n, p) + \ell_1(1, 1, 1) \le 1$$
 or  $\ell_2(m, n, p) + \ell_2(1, 1, 1) \le 1$ .

Equivalently this means

$$\frac{m}{6} + \frac{2n}{3} + \frac{p}{2} + \frac{4}{3} \le 1 \text{ or } \frac{m}{3} + \frac{n}{3} + \frac{p}{2} + \frac{7}{6} \le 1, \ m, n, p \ge 0.$$

Clearly there are no such monomials so that  $p_g(D_4, 0) = 0$  as expected.

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